
PISO-CAN Series

Linux DeviceNet Master Library

PISO-CAN 200/400
PISO-CAN 200U/400U
PISO-CAN 200E
PCM-CAN 200/200P

User Manual

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Tables of Contents

1. CAN DeviceNet Master Library Function Description	4
1.1 Table of Error Code and Error ID.....	5
1.2 Function Descriptions.....	9
1.3 PISO-CAN Series DeviceNet Library FUNCTIONS.....	12
1.3.1 DNM_GetDriverVersion.....	12
1.3.2 DNM_GetLibraryVersion	12
1.3.3 DNM_Open.....	12
1.3.4 DNM_Close.....	13
1.3.5 DNM_Online.....	13
1.3.6 DNM_Offline.....	14
1.3.7 DNM_ChangeMACID.....	14
1.3.8 DNM_ChangeBaudrate	15
1.3.9 DNM_AddDevice	15
1.3.10 DNM_RemoveDevice	16
1.3.11 DNM_ConfigExplicitMsg.....	16
1.3.12 DNM_SetAttribute.....	17
1.3.13 DNM_GetAttribute.....	18
1.3.14 DNM_CheckExplicitMsgConnectionStatus	19
1.3.15 DNM_ConfigPoll	20
1.3.16 DNM_CheckPollConnectionStatus	20
1.3.17 DNM_ReadPollInputData	21
1.3.18 DNM_WritePollOutputData	22
1.3.19 DNM_ConfigBitStrobe.....	22
1.3.20 DNM_ReadBitStrobe	23
1.3.21 DNM_CheckBitStrobeConnectionStatus.....	24
1.3.22 DNM_ConfigCOS	24
1.3.23 DNM_ConfigCyclic.....	25
1.3.24 DNM_ReadCOSInputData.....	26
1.3.25 WriteCOSOutputData	27
1.3.26 DNM_ReadCyclicInputData.....	27
1.3.27 DNM_WriteCyclicOutputData.....	28
1.3.28 DNM_CheckCOSConnectionStatus	28
1.3.29 DNM_CheckCyclicConnectionStatus	29
1.3.30 DNM_StartDevice.....	30
1.3.31 DNM_StopDevice.....	30
1.3.32 DNM_StartCommunicate.....	31
1.3.33 DNM_StopCommnuicate	32
1.3.34 DNM_GetAllDeviceMACID.....	32
1.3.35 DNM_GetOwnership	33
1.3.36 DNM_CheckFaultNode.....	33
1.3.37 DNM_GetAllFaultNode	34
1.3.38 DNM_ChangeFaultMACID.....	34
1.3.39 DNM_GetDeviceStatus	35
1.3.40 DNM_SetPollFrequency.....	35
1.3.41 DNM_SetBitStrobeFrequency.....	36

2.	PISO-CAN Series DeviceNet Library Demo For Linux	37
2.1	Demo code “candnm_a”	37
2.1.1	<i>The DeviceNet Master Online.....</i>	<i>37</i>
2.1.2	<i>The Explicit Message Application.....</i>	<i>38</i>
2.1.3	<i>Master Communicate With Slave Device.....</i>	<i>39</i>

1.CAN DeviceNet Master Library Function Description

The CAN DeviceNet Master static library is the collection of function calls of the PISO-CAN series boards for linux kernel 2.6.x system. The application structure is presented as following figure. The user application program developed by C (C++) language can call library “libdnm.a” in user mode.

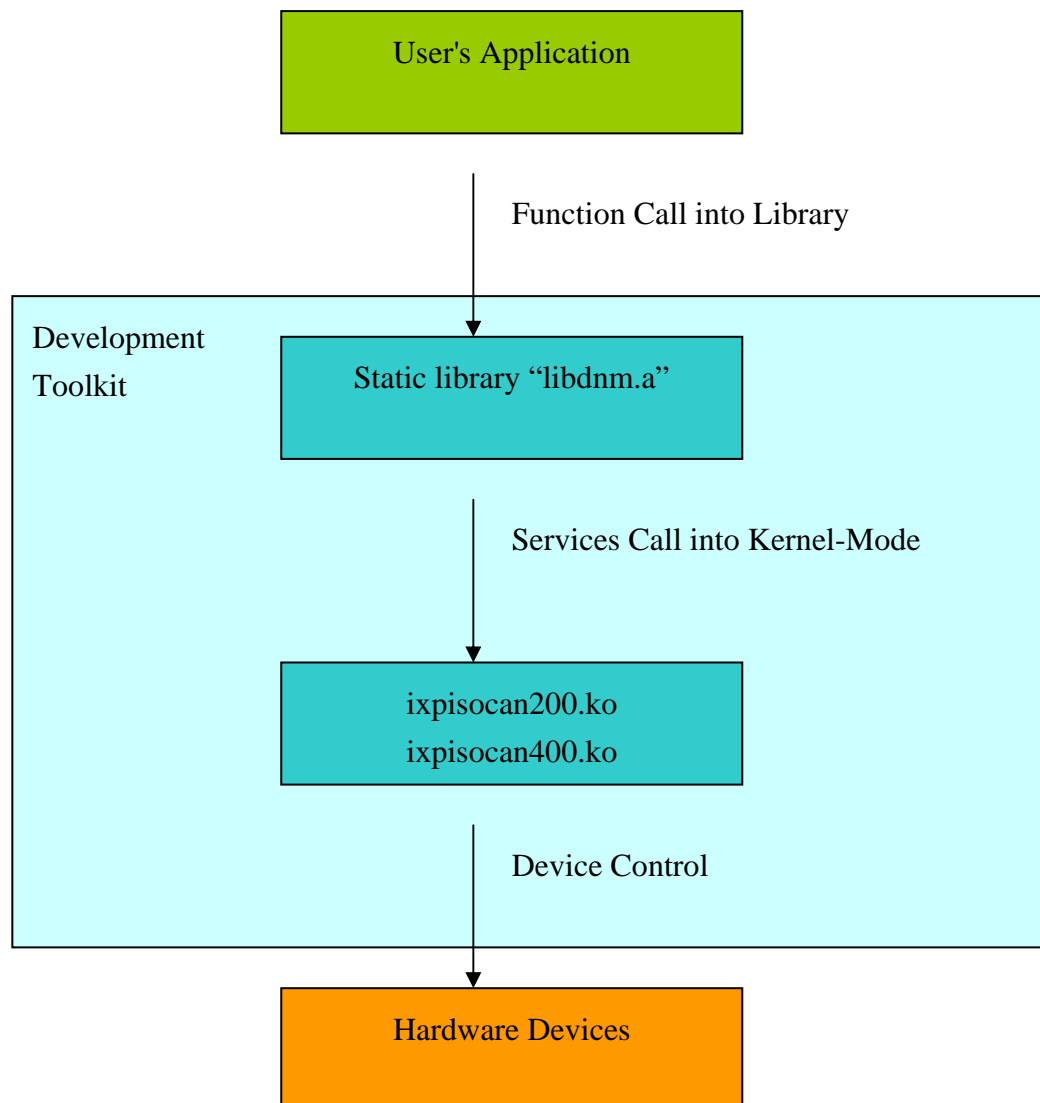


Figure 1.1

1.1 Table of Error Code and Error ID

Error Code	Error ID	Error String
0	DNM_NOERROR	OK (No error !)
1	DNM_OPEN_ERROR	Open CAN DeviceNet master device failure
2	DNM_CLOSE_ERROR	Close CAN DeviceNet master device failure
3	DNM_PORT_ALREADY_ONLINE	CAN port is already online
4	DNM_MACID_ERROR	The MAC id exceed the range between 0 ~ 63
5	DNM_BAUDRATE_ERROR	The baud rate isn't 125, 250 and 500
6	DNM_PORT_INIT_ERROR	CAN port initial error
7	DNM_PORT_CONFIG_ERROR	Configure CAN port error
8	DNM_ENABLERXIRQ_ERROR	Enable CAN port interrupt error
9	DNM_SENDMSG_ERROR	Send CAN message error
10	DNM_ONLINE_ERROR	Master MAC ID is duplicate in the DeviceNet network
11	DNM_DUPLICATE_MACID_TIMEOUT	It is timeout when waiting for the duplicate MAC ID message
12	DNM_ADDTHREAD_ERROR	Create the thread of connection object error
13	DNM_RESUMETHREAD_ERROR	Resume thread error
14	DNM_MASTER_STATE_ERROR	The master is in illegal state
15	DNM_OFFLINE_ERROR	The offline function fail
16	DNM_CHANGE_MACID_ERROR	Change master MAC id error
17	DNM_CHANGE_BAUDRATE_ERROR	Change master baud rate error
18	DNM_DEVICE_IN_SCANLIST	The device is in master scan list
19	DNM_DEVICE_NOT_IN_SCANLIST	The device isn't in master scan list

Error Code	Error ID	Error String
20	DNM_EXPLICITMSG_NOT_CONFIG	The device doesn't configure explicit message connection
21	DNM_CONFIG_EXPLICITMSG_ERROR	Configure slave explicit message connection error
22	DNM_POLL_NOT_CONFIG	The device doesn't configure poll I/O connection
23	DNM_CONFIG_POLL_ERROR	Configure slave poll I/O connection error
24	DNM_WRITE_POLL_OUTPUT_DATA_LENGTH_ERROR	The data length is error when sending poll I/O data
25	DNM_BITSTROBE_NOT_CONFIG	The device doesn't configure bit-strobe I/O connection
26	DNM_CONFIG_BITSTROBE_ERROR	Configure slave bit-strobe I/O connection error
27	DNM_COS_CYCLIC_NOT_CONFIG	The device doesn't configure COS/Cyclic I/O connection
28	DNM_CONFIG_COS_CYCLIC_ERROR	Configure slave COS/Cyclic I/O connection error
29	DNM_STROBE_REQUEST_THREAD_NOT_EXIST	The master has errors when creating Bit-Strobe requester thread
30	DNM_SUSPEND_STROBE_REQUEST_THREAD_ERROR	The master has errors when suspending Bit Strobe requester thread
31	DNM_THREAD_CANCEL_ERROR	The master has errors when cancel connection-object thread
32	DNM_SET_ATTRIBUTE_DATA_IS_EMPTY	The data is empty when setting attribute
33	DNM_DEVICE_IS_UNCONNECTED	The device doesn't establish the connection. Maybe the configuration has some error.
34	DNM_DEVICE_IS_CONNECTING	The device is connecting now.
35	DNM_SET_ATTRIBUTE_RESPONSE_TIMEOUT	The device doesn't response within specific time.
Error Code	Error ID	Error String

36	DNM_SET_ATTRIBUTE_FRAGMENT_ACK_TIMEOUT	It is timeout when waiting for ACK message
37	DNM_SET_ATTRIBUTE_RESPONSE_ERROR	The device response error when setting attribute
38	DNM_SET_ATTRIBUTE_ACK_ERROR	Setting attribute ACK message error
39	DNM_WAIT_BUFFER_RESPONSE_TIMEOUT	It is timeout when waiting for the destination device response
40	DNM_GET_ATTRIBUTE_RESPONSE_TIMEOUT	The device doesn't response within specific time.
41	DNM_GET_ATTRIBUTE_RESPONSE_ERROR	The device response error when getting attribute
42	DNM_CREATE_EXPLICITMSG_THREAD_ERROR	The master create explicit thread error
43	DNM_DEVICE_ERROR	MACID Error or Power off.
44	DNM_COS_CYCLIC_ALREADY_CONFIG	This message means that the COS/Cyclic connection has been configured and started device, so the poll connection can not be configured.
45	DNM_COS_CYCLIC_CONNECT_DUPLICATE	It is illegal when configuring both COS and Cyclic connections in one device.
46	DNM_SET_POLL_INPUT_LEN_ERROR	The poll input length you set doesn't match with the device length.
47	DNM_SET_POLL_OUTPUT_LEN_ERROR	The poll output length you set doesn't match with the device length.
48	DNM_SET_BITSTROBE_INPUT_LEN_ERROR	The Bit-Strobe input length you set doesn't match with the device length.
49	DNM_WRITE_COS_OUTPUT_LEN_ERROR	The data length is error when sending COS I/O data.
Error Code	Error ID	Error String

50	DNM_WRITE_CYCLIC_OUTPUT_LEN_ERROR	The data length is error when sending Cyclic I/O data.
51	DNM_SET_COS_INPUT_LEN_ERROR	The COS input length doesn't match with the device length.
52	DNM_SET_CYCLIC_INPUT_LEN_ERROR	The Cyclic input length you set doesn't match with the device length.
53	DNM_SET_COS_OUTPUT_LEN_ERROR	The COS output length you set doesn't match with the device length.
54	DNM_SET_CYCLIC_OUTPUT_LEN_ERROR	The Cyclic output length you set doesn't match with the device length.
55	DNM_GET_OWNERSHIP_ERROR	The Master can not get the ownership.
56	DNM_MASTER_NOT_GET_OWNERSHIP	The Master has not got the ownership yet.
57	DNM_BITSTROBE_NO_RESPONSE	The Bit-Strobe connection has no response
58	DNM_BITSTROBE_RESPONSE_DATA_ERROR	The Bit-Strobe connection response error messages.
59	DNM_POLL_NO_RESPONSE	The Poll connection has no response
60	DNM_POLL_RESPONSE_DATA_ERROR	The Poll connection response error message.
61	DNM_POLL_FRAGMENT_ERROR	The device has fragment errors
62	DNM_COS_CYCLIC_NO_RESPONSE	The COS/Cyclic connection has no response
63	DNM_COS_CYCLIC_RESPONSE_DATA_ERROR	The COS/Cyclic connection response error messages
64	DNM_COS_CYCLIC_FRAGMENT_ERROR	The COS/Cyclic connection has fragment errors
65	DNM_NORESPONSE	The slave device no response

Table 1.1

1.2 Function Descriptions

Function Definition
char * DNM_GetDriverVersion(void)
char * DNM_GetLibraryVersion(void)
DWORD DNM_Open(BYTE BoardNo, BYTE Port)
DWORD DNM_Close(BYTE BoardNo, BYTE Port)
DWORD DNM_Online(BYTE BoardNo , BYTE Port , DWORD Baudrate , DWORD Macid)
DWORD DNM_Offline(BYTE BoardNo , BYTE Port)
DWORD DNM_ChangeMACID(BYTE BoardNo , BYTE Port , DWORD Macid)
DWORD DNM_ChangeBaudrate(BYTE BoardNo, BYTE Port, DWORD Baudrate)
DWORD DNM_AddDevice(BYTE BoardNo , BYTE Port , DWORD DesMacID)
DWORD DNM_RemoveDevice(BYTE BoardNo, BYTE Port, DWORD DesMacID)
DWORD DNM_ConfigExplicitMsg(BYTE BoardNo , BYTE Port , DWORD DesMacID , WORD watchdog_timeout_action)
DWORD DNM_SetAttribute(BYTE BoardNo , BYTE Port , DWORD DesMacID , WORD ClassID , BYTE InstanceID , BYTE AttributeID , BYTE *SetValue , DWORD Length)
DWORD DNM_GetAttribute(BYTE BoardNo, BYTE Port, DWORD DesMacID, WORD ClassID, BYTE InstanceID, BYTE AttributeID, BYTE *GetValue, DWORD *Length)
DWORD DNM_CheckExplicitMsgConnectionStatus(BYTE BoardNo , BYTE Port , DWORD DesMacID)
DWORD DNM_ConfigPoll(BYTE BoardNo , BYTE Port , DWORD DesMacID , WORD produced_connection_size,WORD consumed_connection_size,WORD expected_packet_rate,WORD watchdog_timeout_action)
DWORD DNM_ReadPollInputData(BYTE BoardNo, BYTE Port, DWORD DesMacID ,BYTE *DataBuf ,DWORD *DataLength)
DWORD DNM_WritePollOutputData(BYTE BoardNo, BYTE Port, DWORD DesMacID, BYTE *DataBuf, DWORD DataLength)
DWORD DNM_CheckPollConnectionStatus(BYTE BoardNo , BYTE Port , DWORD DesMacID)
DWORD DNM_ConfigBitStrobe(BYTE BoardNo, BYTE Port, DWORD DesMacID, WORD produced_connection_size, WORD expected_packet_rate, WORD watchdog_timeout_action)

Function Definition
DWORD DNM_ReadBitStrobe(BYTE BoardNo, BYTE Port, DWORD DesMacID, BYTE *DataBuf, DWORD *DataLength)
DWORD DNM_CheckBitStrobeConnectionStatus(BYTE BoardNo , BYTE Port , DWORD DesMacID)
DWORD DNM_ConfigCOS(BYTE BoardNo, BYTE Port, DWORD DesMacID, WORD produced_connection_size, WORD consumed_connection_size, BYTE isnonack, WORD expected_packet_rate, WORD watchdog_timeout_action)
DWORD DNM_ConfigCyclic(BYTE BoardNo, BYTE Port, DWORD DesMacID, WORD produced_connection_size, WORD consumed_connection_size, BYTE isnonack, WORD expected_packet_rate, WORD watchdog_timeout_action)
DWORD DNM_ReadCOSInputData(BYTE BoardNo, BYTE Port, DWORD DesMacID, BYTE *DataBuf, DWORD *DataLength)
DWORD DNM_WriteCOSOutputData(BYTE BoardNo, BYTE Port, DWORD DesMacID, BYTE *DataBuf, DWORD DataLength)
DWORD DNM_ReadCyclicInputData(BYTE BoardNo, BYTE Port, DWORD DesMacID, BYTE *DataBuf, DWORD *DataLength)
DWORD DNM_WriteCyclicOutputData(BYTE BoardNo, BYTE Port, DWORD DesMacID, BYTE *DataBuf, DWORD DataLength)
DWORD DNM_CheckCOSConnectionStatus(BYTE BoardNo, BYTE Port, DWORD DesMacID)
DWORD DNM_CheckCyclicConnectionStatus(BYTE BoardNo, BYTE Port, DWORD DesMacID)
DWORD DNM_StartDevice(BYTE BoardNo, BYTE Port, DWORD DesMacID)
DWORD DNM_StopDevice(BYTE BoardNo, BYTE Port, DWORD DesMacID)
DWORD DNM_StartCommunicate(BYTE BoardNo, BYTE Port)
DWORD DNM_StopCommunicate(BYTE BoardNo, BYTE Port)
DWORD DNM_GetOwnership(BYTE BoardNo, BYTE Port)
DWORD DNM_CheckFaultNode(BYTE BoardNo, BYTE Port)
DWORD DNM_GetAllFaultNode(BYTE BoardNo, BYTE Port, WORD *VendorID, DWORD *SerialNo, BYTE *NodeCount)
DWORD DNM_ChangeFaultMACID(BYTE BoardNo, BYTE Port, WORD VendorID, DWORD SerialNo, BYTE NewMacID)
DWORD DNM_GetAllDeviceMACID(BYTE BoardNo, BYTE Port, BYTE *AllMacID, BYTE *DeviceCount)
DWORD DNM_GetDeviceStatus(BYTE BoardNo, BYTE Port, BYTE DesMacID)

Function Definition
DWORD DNM_SetPollFrequency(WORD Frequency)
DWORD DNM_SetBitStrobeFrequency(WORD Frequency)

Table 1.2

1.3 PISO-CAN Series DeviceNet Library FUNCTIONS

1.3.1 DNM_GetDriverVersion

- **Description:**
To get the linux IxPCI driver version.
- **Syntax:**
char * DNM_GetDriverVersion(void)
- **Parameter:**
None
- **Return:**
The linux driver of ixpci version.

1.3.2 DNM_GetLibraryVersion

- **Description:**
To get the linux CAN DeviceNet library version.
- **Syntax:**
char * DNM_GetLibraryVersion(void)
- **Parameter:**
None
- **Return:**
The CAN DeviceNet master library version.

1.3.3 DNM_Open

- **Description:**
To open the device file of PISO-CAN series DeviceNet master.
- **Syntax:**
DWORD DNM_Open(BYTE BoardNo, BYTE Port)
- **Parameter:**
BoardNo: The board number (1~4) of PISO-CAN series board
Port: The port number (1~4) of PISO-CAN series board
- **Return:**
"DNM_NOERROR"
"DNM_OPEN_ERROR"
(Please refer to "Section 1.1 Error Code")

1.3.4 DNM_Close

- **Description :**
To close PISO-CAN series DeviceNet master device file.
- **Syntax :**
WORD DNM_Close(BYTE BoardNo, BYTE Port)
- **Parameter :**
BoardNo: The board number (1~4) of PISO-CAN series board
Port: The port number (1~4) of PISO-CAN series board
- **Return:**
"DNM_NOERROR"
"DNM_CLOSE_ERROR"
"DNM_OPEN_ERROR"
(Please refer to "Section 1.1 Error Code").

1.3.5 DNM_Online

- **Description :**
The function can make the CAN Port online. When calling this function, the CAN port will check the duplicate MAC ID. After the function work well, the CAN port become the DeviceNet master port. Then, the port will also transfer into online state in the DeviceNet network.
- **Syntax :**
DWORD DNM_Online(BYTE BoardNo , BYTE Port , DWORD Baudrate, DWORD Macid);
- **Parameter :**
BoardNo: [input] PISO-CAN series board number (1~7)
Port: [input] CAN port number (1~2 or 1~4)
Baudrate: [input] DeviceNet baud rate (125, 250 and 500)
Macid: [input] DeviceNet Master MAC ID (0~63)
- **Return:**
"DNM_OPEN_ERROR"
"DNM_PORT_ALREADY_ONLINE"
"DNM_MACID_ERROR"
"DNM_BAUDRATE_ERROR "
"DNM_PORT_INIT_ERROR "
"DNM_PORT_CONFIG_ERROR "
"DNM_ENABLERXIRQ_ERROR "

“DNM_SENDDMSG_ERROR “
“DNM_ONLINE_ERROR “
“DNM_ADDTHREAD_ERROR “
“DNM_RESUMETHREAD_ERROR “
“DNM_NOERROR”
(Please refer to "Section 1.1 Error Code").

1.3.6 DNM_Offline

- **Description :**
The method makes the CAN port offline. After calling this function, the CAN Port will disable the functions of the DeviceNet master device. It will transfer into offline state in DeviceNet network. In this status, the CAN port will not communicate with any slave devices.
 - **Syntax :**
DWORD DNM_Offline(BYTE BoardNo , BYTE Port)
 - **Parameter :**
BoardNo: [input] PISO-CAN series board number (1~7)
Port: [input] CAN port number (1~2 or 1~4)
 - **Return:**
“DNM_OPEN_ERROR”
“DNM_MASTER_STATE_ERROR”
“DNM_ADDTHREAD_ERROR “
“DNM_RESUMETHREAD_ERROR “
“DNM_NOERROR”
(Please refer to "Section 1.1 Error Code").
-

1.3.7 DNM_ChangeMACID

- **Description :**
When the CAN port is online, this function can change the MAC ID of this master port.
- **Syntax :**
DWORD DNM_ChangeMACID(BYTE BoardNo , BYTE Port , DWORD Macid)
- **Parameter :**
BoardNo: [input] PISO-CAN series board number (1~7)
Port: [input] CAN port number (1~2 or 1~4)
Macid: [input] DeviceNet Master MAC ID (0~63)

-
- **Return:**
"DNM_OPEN_ERROR"
"DNM_MASTER_STATE_ERROR"
"DNM_MACID_ERROR "
"DNM_CHANGE_MACID_ERROR "
"DNM_NOERROR"
(Please refer to "Section 2.1 Error Code").

1.3.8 DNM_ChangeBaudrate

- **Description :**
When the master CAN port is online, this function can change its baud rate.
- **Syntax :**
DWORD DNM_ChangeBaudrate(BYTE BoardNo, BYTE Port, DWORD Baudrate)
- **Parameter :**
BoardNo: [input] PISO-CAN series board number (1~7)
Port: [input] CAN port number (1~2 or 1~4)
Baudrate: [input] DeviceNet baud rate (125, 250 and 500)
- **Return:**
"DNM_OPEN_ERROR"
"DNM_MASTER_STATE_ERROR"
"DNM_CHANGE_BAUDRATE_ERROR"
"DNM_NOERROR"
(Please refer to "Section 1.1 Error Code").

1.3.9 DNM_AddDevice

- **Description :**
This function can add the slave devices into the scan list of the CAN port of DeviceNet master. Before using this function, the port must be online. The master port will use the scan list to store the information of the device. And the master port just can communicate with the slave devices in this scan list.
- **Syntax :**
DWORD DNM_AddDevice(BYTE BoardNo , BYTE Port , DWORD DesMacID)

-
- **Parameter :**
BoardNo: [input] PISO-CAN series board number (1~7)
Port: [input] CAN port number (1~2 or 1~4)
DestMACID: [input] Destination DeviceNet MAC ID (0~63)
 - **Return:**
“DNM_OPEN_ERROR”
“DNM_MACID_ERROR”
“DNM_MASTER_STATE_ERROR “
“DNM_DEVICE_IN_SCANLIST “
“DNM_MACID_ERROR “
“DNM_NOERROR “
(Please refer to "Section 1.1 Error Code").

1.3.10 DNM_RemoveDevice

- **Description :**
The function would remove the slave device from the scan list of this DeviceNet master port. And the Master will also remove the device information from scan list.
- **Syntax :**
DWORD DNM_RemoveDevice(BYTE BoardNo, BYTE Port, DWORD DesMacID)
- **Parameter :**
BoardNo: [input] PISO-CAN series board number (1~7)
Port: [input] CAN port number (1~2 or 1~4)
DestMACID: [input] Destination DeviceNet MAC ID (0~63)
- **Return:**
“DNM_OPEN_ERROR”
“DNM_MACID_ERROR”
“DNM_MASTER_STATE_ERROR“
“DNM_DEVICE_NOT_IN_SCANLIST “
“DNM_NOERROR “
(Please refer to "Section 1.1 Error Code").

1.3.11 DNM_ConfigExplicitMsg

- **Description :**
The function is used to configure the Explicit Message connection. This is the based connection of the DeviceNet network. Before calling the

function, the destination slave device must have been added into the master scan list by using the “DNM_AddDevice” function.

- **Syntax :**

DWORD DNM_ConfigExplicitMsg(BYTE BoardNo , BYTE Port ,
DWORD DesMacID , WORD watchdog_timeout_action)

- **Parameter :**

BoardNo: [input] PISO-CAN series board number (1~7)

Port: [input] CAN port number (CAN200): 1~2; (CAN400): 1~4

DestMACID: [input] Destination DeviceNet MAC ID (0~63)

watchdog_timeout_action: [input] The action when watchdog is timeout.

According to the DeviceNet specification, the Explicit Message Connection can be set 1 or 3.

1 : Auto Delete. This means when watchdog is timeout, the connection will be deleted automatically. This is the default value.

3 : Deferred Delete. This means when watchdog is timeout, the connection will transfer to the deferred state. It would wait until its child connections have been delete. If the connection has no child, it will be deleted.

- **Return:**

“DNM_OPEN_ERROR”

“DNM_MACID_ERROR”

“DNM_MASTER_STATE_ERROR”

“DNM_DEVICE_NOT_IN_SCANLIST”

“DNM_CONFIG_EXPLICITMSG_ERROR”

“DNM_NOERROR”

(Please refer to "Section 1.1 Error Code").

1.3.12 DNM_SetAttribute

- **Description :**

The method is used to set the attribute of the specific device's instance. Before calling this function, the Explicit Message connection must be established first.

- **Syntax :**

DWORD DNM_SetAttribute(BYTE BoardNo , BYTE Port , DWORD
DesMacID , WORD ClassID , BYTE InstanceID , BYTE AttributeID ,
BYTE *SetValue , DWORD Length)

- **Parameter :**

BoardNo: [input] PISO-CAN series board number (1~7)

Port: [input] CAN port number (1~2 or 1~4)

DestMACID: [input] The destination DeviceNet MAC ID (0~63)

ClassID: [input] The Class ID of the destination device.

InstanceID:[input] The Instance ID of the destination device.

AttributeID: [input] The Attribute ID of the destination device.

SetValue: [input] The value will be set to the destination device.

Length: [input] The length (in byte) of the SetValue.

- **Return:**

"DNM_OPEN_ERROR"

"DNM_MACID_ERROR"

"DNM_MASTER_STATE_ERROR"

"DNM_DEVICE_NOT_IN_SCANLIST"

"DNM_SET_ATTRIBUTE_DATA_IS_EMPTY"

"DNM_DEVICE_IS_UNCONNECTED"

"DNM_SENDMSG_ERROR"

"DNM_SET_ATTRIBUTE_RESPONSE_TIMEOUT"

"DNM_SET_ATTRIBUTE_FRAGMENT_ACK_TIMEOUT"

"DNM_SET_ATTRIBUTE_RESPONSE_ERROR"

"DNM_SET_ATTRIBUTE_ACK_ERROR"

"DNM_SET_ATTRIBUTE_FRAGMENT_ACK_TIMEOUT"

"DNM_NOERROR"

(Please refer to "Section 1.1 Error Code").

1.3.13 DNM_GetAttribute

- **Description :**

This function is used to get the attribute value of the specific instance id of device. Before calling this function, the Explicit Message connection must be established first.

- **Syntax :**

DWORD DNM_GetAttribute(BYTE BoardNo, BYTE Port, DWORD DesMacID, WORD ClassID, BYTE InstanceID, BYTE AttributeID, BYTE *GetValue, DWORD *Length)

- **Parameter :**

BoardNo: [input] PISO-CAN series board number (1~7)

Port: [input] CAN port number (1~2 or 1~4)

DestMACID: [input] The destination DeviceNet MAC ID (0~63)
ClassID: [input] The Class ID of the destination device.
InstanceID: [input] The Instance ID of the destination device.
AttributeID: [input] The Attribute ID of the destination device.
GetValue: [output] The variable will return the data form the device.
Length: [output] The length (in byte) of the GetValue.

- **Return:**
"DNM_OPEN_ERROR"
"DNM_MACID_ERROR"
"DNM_MASTER_STATE_ERROR"
"DNM_DEVICE_NOT_IN_SCANLIST"
"DNM_DEVICE_IS_UNCONNECTED"
"DNM_SENDMSG_ERROR"
"DNM_GET_ATTRIBUTE_RESPONSE_TIMEOUT"
"DNM_GET_ATTRIBUTE_RESPONSE_ERROR"
"DNM_NOERROR"
(Please refer to "Section 1.1 Error Code").

1.3.14 DNM_CheckExplicitMsgConnectionStatus

- **Description :**
The function is used to check the connection status of Explicit Message.
- **Syntax :**
DWORD DNM_CheckExplicitMsgConnectionStatus(BYTE BoardNo ,
BYTE Port , DWORD DesMacID)
- **Parameter :**
BoardNo: [input] PISO-CAN series board number (1~7)
Port: [input] CAN port number (CAN200): 1~2; (CAN400): 1~4
DestMACID: [input] Destination DeviceNet MAC ID (0~63)
- **Return:**
"DNM_OPEN_ERROR"
"DNM_MACID_ERROR"
"DNM_MASTER_STATE_ERROR"
"DNM_DEVICE_NOT_IN_SCANLIST"
"DNM_EXPLICITMSG_NOT_CONFIG"
"DNM_DEVICE_ERROR"
"DNM_NOERROR"
(Please refer to "Section 1.1 Error Code").

1.3.15 DNM_ConfigPoll

- **Description :**

This method is used to configure the Poll connection of the specific slave device. The master port can get/set the data via the connection, according to the produced/consumed connection path of this slave device. The connection timeout and watchdog timeout action can be set from "expected_packet_rate" and "watchdog_timeout_action" parameters.

- **Syntax :**

DWORD DNM_ConfigPoll(BYTE BoardNo , BYTE Port , DWORD DesMacID , WORD produced_connection_size,WORD consumed_connection_size,WORD expected_packet_rate,WORD watchdog_timeout_action);

- **Parameter :**

BoardNo: [input] PISO-CAN series board number (1~7)

Port: [input] CAN port number (1~2 or 1~4)

DestMACID: [input] The destination DeviceNet MAC ID (0~63)

produced_connection_size: [input] The data length of the input channel of the device.

consumed_connection_size: [input] The data length of the input channel of the device.

expected_packet_rate: [input] The default value is 0X9C4 (2500)

watchdog_timeout_action: [input] The default value is 0

- **Return:**

"DNM_OPEN_ERROR"

"DNM_MACID_ERROR"

"DNM_MASTER_STATE_ERROR"

"DNM_DEVICE_NOT_IN_SCANLIST"

"DNM_COS_CYCLIC_ALREADY_CONFIG"

"DNM_NOERROR"

(Please refer to "Section 1.1 Error Code").

1.3.16 DNM_CheckPollConnectionStatus

- **Description:**

The function is used to check the Poll connection status.

- **Syntax:**

DWORD DNM_CheckPollConnectionStatus(BYTE BoardNo , BYTE Port , DWORD DesMacID);

- **Parameter:**

BoardNo: [input] PISO-CAN series board number (1~7)

Port: [input] CAN port number (1~2 or 1~4)

DestMACID: [input] The destination DeviceNet MAC ID (0~63)

- **Return:**

“DNM_OPEN_ERROR”

“DNM_MACID_ERROR”

“DNM_MASTER_STATE_ERROR”

“DNM_DEVICE_NOT_IN_SCANLIST”

“DNM_POLL_NOT_CONFIG”

“DNM_SET_POLL_INPUT_LEN_ERROR”

“DNM_SET_POLL_OUTPUT_LEN_ERROR”

“DNM_DEVICE_ERROR”

“DNM_DEVICE_IS_UNCONNECTED”

“DNM_NOERROR”

(Please refer to "Section 1.1 Error Code").

1.3.17 DNM_ReadPollInputData

- **Description:**

This function is to get the data according with the produced connection path of the specific slave device via the Poll connection.

- **Syntax:**

DWORD DNM_ReadPollInputData(BYTE BoardNo, BYTE Port, DWORD DesMacID ,BYTE *DataBuf ,DWORD *DataLength)

- **Parameter:**

BoardNo: [input] PISO-CAN series board number (1~7)

Port: [input] CAN port number (1~2 or 1~4)

DestMACID: [input] The destination DeviceNet MAC ID (0~63)

DataBuf: [output] The data of the input channel

DataLength: [output] The length (in Byte) of the data

- **Return:**

“DNM_OPEN_ERROR”

“DNM_MACID_ERROR”

“DNM_MASTER_STATE_ERROR”

“DNM_DEVICE_NOT_IN_SCANLIST”

“DNM_DEVICE_IS_UNCONNECTED”

“DNM_NOERROR”

(Please refer to "Section 1.1 Error Code")

1.3.18 DNM_WritePollOutputData

- **Description:**

The function will set the data according with the path of consumed connection of the specific device via the Poll connection.

- **Syntax:**

DWORD DNM_WritePollOutputData(BYTE BoardNo, BYTE Port, DWORD DesMacID, BYTE *DataBuf, DWORD DataLength)

- **Parameter:**

BoardNo: [input] PISO-CAN series board number (1~7)

Port: [input] CAN port number (1~2 or 1~4)

DestMACID: [input] The destination DeviceNet MAC ID (0~63)

DataBuf: [input]The data of the output channel

DataLength: [input]The length(in Byte) of the data

- **Return:**

"DNM_OPEN_ERROR"

"DNM_MACID_ERROR"

"DNM_MASTER_STATE_ERROR"

"DNM_DEVICE_NOT_IN_SCANLIST"

"DNM_DEVICE_IS_UNCONNECTED"

"DNM_WRITE_POLL_OUTPUT_DATALENGTH_ERROR"

"DNM_NOERROR"

(Please refer to "Section 1.1 Error Code")

1.3.19 DNM_ConfigBitStrobe

- **Description:**

The function can configure the Bit-Strobe connection of the specific device. The master port will get the data of the slave devices every period of time via this connection. The connection timeout and watchdog timeout action can be set to "expected_packet_rate" and "watchdog_timeout_action" parameters.

- **Syntax:**

DWORD DNM_ConfigBitStrobe(BYTE BoardNo, BYTE Port, DWORD DesMacID, WORD produced_connection_size, WORD expected_packet_rate, WORD watchdog_timeout_action)

- **Parameter:**

BoardNo: [input] PISO-CAN series board number (1~7)
Port: [input] CAN port number (1~2 or 1~4)
DestMACID: [input] The destination DeviceNet MAC ID (0~63)
produced_connection_size: [input] The data length of the input channel of the device.
expected_packet_rate: [input] The default value is 0X9C4 (2500)
watchdog_timeout_action: [input] The default value is 0

- **Return:**
“DNM_OPEN_ERROR”
“DNM_MACID_ERROR”
“DNM_MASTER_STATE_ERROR”
“DNM_DEVICE_NOT_IN_SCANLIST”
“DNM_NOERROR”
(Please refer to "Section 1.1 Error Code")

1.3.20 DNM_ReadBitStrobe

- **Description:**
The function is used to get the data according with the produced connection path of the specific slave device via the Bit-Strobe connection.
- **Syntax:**
DWORD DNM_ReadBitStrobe(BYTE BoardNo, BYTE Port, DWORD DesMacID, BYTE *DataBuf, DWORD *DataLength)
- **Parameter:**
BoardNo: [input] PISO-CAN series board number (1~7)
Port: [input] CAN port number (1~2 or 1~4)
DestMACID: [input] The destination DeviceNet MAC ID (0~63)
DataBuf: [output] The data of the input channel
DataLength: [output] The length (in Byte) of the data
- **Return:**
“DNM_OPEN_ERROR”
“DNM_MACID_ERROR”
“DNM_MASTER_STATE_ERROR”
“DNM_DEVICE_NOT_IN_SCANLIST”
“DNM_DEVICE_IS_UNCONNECTED”
“DNM_NOERROR”
(Please refer to "Section 1.1 Error Code")

1.3.21 DNM_CheckBitStrobeConnectionStatus

- **Description:**

The function can check the status of the Bit-Strobe connection, which is connected to the specific slave device.

- **Syntax:**

DWORD DNM_CheckBitStrobeConnectionStatus(BYTE BoardNo ,
BYTE Port , DWORD DesMacID)

- **Parameter:**

BoardNo: [input] PISO-CAN series board number (1~7)

Port: [input] CAN port number (1~2 or 1~4)

DestMACID: [input] The destination DeviceNet MAC ID (0~63).

- **Return:**

“DNM_OPEN_ERROR”

“DNM_MACID_ERROR”

“DNM_MASTER_STATE_ERROR”

“DNM_DEVICE_NOT_IN_SCANLIST”

“DNM_BITSTROBE_NOT_CONFIG”

“DNM_SET_BITSTROBE_INPUT_LEN_ERROR”

“DNM_DEVICE_ERROR”

“DNM_NOERROR”

(Please refer to "Section 1.1 Error Code")

1.3.22 DNM_ConfigCOS

- **Description:**

This function is used to configure the COS connection. This connection will get the data every period of time, when the connection of Poll does not exist. If the Poll connection exists, the connection will set the data when needed and get the data when the specific status changed. The connection timeout and watchdog timeout action can be set from “expected_packet_rate” and “watchdog_timeout_action” parameters.

- **Syntax:**

DWORD DNM_ConfigCOS(BYTE BoardNo, BYTE Port, DWORD
DesMacID, WORD produced_connection_size, WORD
consumed_connection_size, BYTE isnonack, WORD
expected_packet_rate, WORD watchdog_timeout_action)

- **Parameter:**

BoardNo: [input] PISO-CAN series board number (1~7)

Port: [input] CAN port number (1~2 or 1~4)
DestMACID: [input] The destination DeviceNet MAC ID (0~63)
produced_connection_size: [input] The data length of the input channel
consumed_connection_size: [input] The data length of the output
channel
isnonack:[input] The default value is FALSE
expected_packet_rate: [input] The default value is 0X9C4 (2500)
watchdog_timeout_action: [input] The default value is 0;

- **Return:**
“DNM_OPEN_ERROR”
“DNM_MACID_ERROR”
“DNM_MASTER_STATE_ERROR”
“DNM_DEVICE_NOT_IN_SCANLIST”
“DNM_COS_CYCLIC_CONNECT_DUPLICATE”
“DNM_NOERROR”
(Please refer to "Section 1.1 Error Code")

1.3.23 DNM_ConfigCyclic

- **Description:**
This function is used to configure the Cyclic connection. The connection will get the data according to the produced connection path of the specific slave device channel every period of time, when the connection of Poll does not exist. If the Poll connection exists, the master port will get the data every period of time and could set the data via the connection. The connection timeout and watchdog timeout action can be set from “expected_packet_rate” and “watchdog_timeout_action” parameters.
- **Syntax:**
DWORD DNM_ConfigCyclic(BYTE BoardNo, BYTE Port, DWORD DesMacID, WORD produced_connection_size, WORD consumed_connection_size, BYTE isnonack, WORD expected_packet_rate, WORD watchdog_timeout_action)
- **Parameter:**
BoardNo: [input] PISO-CAN series board number (1~7)
Port: [input] CAN port number (1~2 or 1~4)
DestMACID: [input] The destination DeviceNet MAC ID (0~63)
produced_connection_size: [input] The data length of the input channel.

consumed_connection_size: [input] The data length of the output channel.

isnonack:[input] The default value is FALSE

expected_packet_rate: [input] The default value is 0X9C4 (2500)

watchdog_timeout_action: [input] The default value is 0.

- **Return:**

“DNM_OPEN_ERROR”

“DNM_MACID_ERROR”

“DNM_MASTER_STATE_ERROR”

“DNM_DEVICE_NOT_IN_SCANLIST”

“DNM_COS_CYCLIC_CONNECT_DUPLICATE”

“DNM_NOERROR”

(Please refer to "Section 1.1 Error Code")

1.3.24 DNM_ReadCOSInputData

- **Description:**

This method is used to read the data of the specific slave device via the COS connection.

- **Syntax:**

DWORD DNM_ReadCOSInputData(BYTE BoardNo, BYTE Port, DWORD DesMacID, BYTE *DataBuf, DWORD *DataLength)

- **Parameter:**

BoardNo: [input] PISO-CAN series board number (1~7)

Port: [input] CAN port number (1~2 or 1~4)

DestMACID: [input] The destination DeviceNet MAC ID (0~63)

DataBuf: [output] The data of the input channel

DataLength: [output] The length(in Byte) of the data

- **Return:**

“DNM_OPEN_ERROR”

“DNM_MACID_ERROR”

“DNM_MASTER_STATE_ERROR”

“DNM_DEVICE_NOT_IN_SCANLIST”

“DNM_COS_CYCLIC_NOT_CONFIG”

“DNM_DEVICE_IS_UNCONNECTED”

“DNM_NOERROR”

(Please refer to "Section 1.1 Error Code")

1.3.25 WriteCOSOutputData

- **Description:**

This function is used to set the data according to the consumed connection path of the specific slave device via the COS connection.

- **Syntax:**

DWORD DNM_WriteCOSOutputData(BYTE BoardNo, BYTE Port, DWORD DesMacID, BYTE *DataBuf, DWORD DataLength)

- **Parameter:**

BoardNo: [input] PISO-CAN series board number (1~7)

Port: [input] CAN port number (1~2 or 1~4)

DestMACID: [input] The destination DeviceNet MAC ID (0~63)

DataBuf: [input] The data of the output channel

DataLength: [input] The length (in Byte) of the data

- **Return:**

"DNM_OPEN_ERROR"

"DNM_MACID_ERROR"

"DNM_MASTER_STATE_ERROR"

"DNM_DEVICE_NOT_IN_SCANLIST"

"DNM_WRITE_COS_OUTPUT_LEN_ERROR"

"DNM_DEVICE_IS_UNCONNECTED"

"DNM_NOERROR"

(Please refer to "Section 1.1 Error Code")

1.3.26 DNM_ReadCyclicInputData

- **Description:**

This function is used to get the data according to the produced connection path of the specific slave device via the Cyclic connection.

- **Syntax:**

DWORD DNM_ReadCyclicInputData(BYTE BoardNo, BYTE Port, DWORD DesMacID, BYTE *DataBuf, DWORD *DataLength)

- **Parameter:**

BoardNo: [input] PISO-CAN series board number (1~7)

Port: [input] CAN port number (1~2 or 1~4)

DestMACID: [input] The destination DeviceNet MAC ID (0~63)

DataBuf: [output] The data of the input channel

DataLength: [output] The length(in Byte) of the data.

-
- **Return:**
"DNM_OPEN_ERROR"
"DNM_MACID_ERROR"
"DNM_MASTER_STATE_ERROR"
"DNM_DEVICE_NOT_IN_SCANLIST"
"DNM_COS_CYCLIC_NOT_CONFIG"
"DNM_DEVICE_IS_UNCONNECTED"
"DNM_NOERROR"
(Please refer to "Section 1.1 Error Code")

1.3.27 DNM_WriteCyclicOutputData

- **Description:**
This method is used to set the data according to the consumed connection path of the output channel of the specific slave device.
- **Syntax:**
DWORD DNM_WriteCyclicOutputData(BYTE BoardNo, BYTE Port, DWORD DesMacID, BYTE *DataBuf, DWORD DataLength)
- **Parameter:**
BoardNo: [input] PISO-CAN series board number (1~7)
Port: [input] CAN port number (1~2 or 1~4)
DestMACID: [input] The destination DeviceNet MAC ID (0~63)
DataBuf: [input] The data of the output channel
DataLength: [input] The length (in Byte) of the data
- **Return:**
"DNM_OPEN_ERROR"
"DNM_MACID_ERROR"
"DNM_MASTER_STATE_ERROR"
"DNM_DEVICE_NOT_IN_SCANLIST"
"DNM_WRITE_CYCLIC_OUTPUT_LEN_ERROR"
"DNM_DEVICE_IS_UNCONNECTED"
"DNM_NOERROR"
(Please refer to "Section 1.1 Error Code")

1.3.28 DNM_CheckCOSConnectionStatus

- **Description:**
This function is used to check the status of the COS connection which is connected to the specific slave device.

-
- **Syntax:**
DWORD DNM_CheckCOSConnectionStatus(BYTE BoardNo, BYTE Port, DWORD DesMacID)
 - **Parameter:**
BoardNo: [input] PISO-CAN series board number (1~7)
Port: [input] CAN port number (1~2 or 1~4)
DestMACID: [input] The destination DeviceNet MAC ID (0~63)
 - **Return:**
"DNM_OPEN_ERROR"
"DNM_MACID_ERROR"
"DNM_MASTER_STATE_ERROR"
"DNM_DEVICE_NOT_IN_SCANLIST"
"DNM_COS_CYCLIC_NOT_CONFIG"
"DNM_SET_COS_INPUT_LEN_ERROR"
"DNM_SET_COS_OUTPUT_LEN_ERROR"
"DNM_DEVICE_ERROR"
"DNM_NOERROR"
(Please refer to "Section 1.1 Error Code")

1.3.29 DNM_CheckCyclicConnectionStatus

- **Description:**
This function is used to check the status of the Cyclic connection which is connected to the specific slave device.
- **Syntax:**
DWORD DNM_CheckCyclicConnectionStatus(BYTE BoardNo, BYTE Port, DWORD DesMacID)
- **Parameter:**
BoardNo: [input] PISO-CAN series board number (1~7)
Port: [input] CAN port number (1~2 or 1~4)
DestMACID: [input] The destination DeviceNet MAC ID (0~63)
- **Return:**
"DNM_OPEN_ERROR"
"DNM_MACID_ERROR"
"DNM_MASTER_STATE_ERROR"
"DNM_DEVICE_NOT_IN_SCANLIST"
"DNM_COS_CYCLIC_NOT_CONFIG"
"DNM_SET_COS_INPUT_LEN_ERROR"

"DNM_SET_COS_OUTPUT_LEN_ERROR"

"DNM_DEVICE_ERROR"

"DNM_NOERROR"

(Please refer to "Section 1.1 Error Code")

1.3.30 DNM_StartDevice

- **Description:**

This function is used to start to communicate with the destination slave device.

- **Syntax:**

DWORD DNM_StartDevice(BYTE BoardNo, BYTE Port, DWORD DesMacID)

- **Parameter:**

BoardNo: [input] PISO-CAN series board number (1~7)

Port: [input] CAN port number (1~2 or 1~4)

DestMACID: [input] The destination DeviceNet MAC ID (0~63)

- **Return:**

"DNM_OPEN_ERROR"

"DNM_MACID_ERROR"

"DNM_MASTER_STATE_ERROR"

"DNM_DEVICE_NOT_IN_SCANLIST"

"DNM_DEVICE_IS_CONNECTING"

"DNM_EXPLICITMSG_NOT_CONFIG"

"DNM_POLL_NOT_CONFIG"

"DNM_BITSTROBE_NOT_CONFIG"

"DNM_COS_CYCLIC_NOT_CONFIG"

"DNM_COS_CYCLIC_CONNECT_DUPLICATE"

"DNM_ADDTHREAD_ERROR"

"DNM_RESUMETHREAD_ERROR"

"DNM_NOERROR"

(Please refer to "Section 1.1 Error Code")

1.3.31 DNM_StopDevice

- **Description:**

This function is used to stop to communicate with the destination slave device.

- **Syntax:**

DWORD DNM_StopDevice(BYTE BoardNo, BYTE Port, DWORD DesMacID)

- **Parameter:**

BoardNo: [input] PISO-CAN series board number (1~7)

Port: [input] CAN port number (1~2 or 1~4)

DestMACID: [input] The destination DeviceNet MAC ID (0~63)

- **Return:**

“DNM_OPEN_ERROR”

“DNM_MACID_ERROR”

“DNM_MASTER_STATE_ERROR”

“DNM_DEVICE_NOT_IN_SCANLIST”

“DNM_DEVICE_IS_UNCONNECT”

“DNM_EXPLICITMSG_NOT_CONFIG”

“DNM_POLL_NOT_CONFIG”

“DNM_BITSTROBE_NOT_CONFIG”

“DNM_COS_CYCLIC_NOT_CONFIG”

“DNM_NOERROR”

(Please refer to "Section 1.1 Error Code")

1.3.32 DNM_StartCommunicate

- **Description:**

This function is used to start to communicate with all devices in scan list.

- **Syntax:**

DWORD DNM_StartCommunicate(BYTE BoardNo, BYTE Port)

- **Parameter:**

BoardNo: [input] PISO-CAN series board number (1~7)

Port: [input] CAN port number (1~2 or 1~4).

- **Return:**

“DNM_OPEN_ERROR”

“DNM_MASTER_STATE_ERROR”

“DNM_DEVICE_IS_CONNECTING”

“DNM_EXPLICITMSG_NOT_CONFIG”

“DNM_POLL_NOT_CONFIG”

“DNM_BITSTROBE_NOT_CONFIG”

“DNM_COS_CYCLIC_NOT_CONFIG”

“DNM_COS_CYCLIC_CONNECT_DUPLICATE”

“DNM_ADDTHREAD_ERROR”

“DNM_RESUMETHREAD_ERROR”

“DNM_NOERROR”

(Please refer to "Section 1.1 Error Code")

1.3.33 DNM_StopCommnuicate

- **Description:**

This function is used to stop to communicate with all destination devices in scan list.

- **Syntax:**

DWORD DNM_StopCommunicate(BYTE BoardNo, BYTE Port)

- **Parameter:**

BoardNo: [input] PISO-CAN series board number (1~7)

Port: [input] CAN port number (1~2 or 1~4)

- **Return:**

“DNM_OPEN_ERROR”

“DNM_MASTER_STATE_ERROR”

“DNM_DEVICE_IS_UNCONNECT”

“DNM_EXPLICITMSG_NOT_CONFIG”

“DNM_POLL_NOT_CONFIG”

“DNM_BITSTROBE_NOT_CONFIG”

“DNM_COS_CYCLIC_NOT_CONFIG”

“DNM_NOERROR”

(Please refer to "Section 1.1 Error Code").

1.3.34 DNM_GetAllDeviceMACID

- **Description:**

This function is to get the MAC IDs of all devices in DeviceNet network.

- **Syntax:**

DWORD DNM_GetAllDeviceMACID(BYTE BoardNo, BYTE Port, BYTE *AllMacID, BYTE *DeviceCount)

- **Parameter:**

BoardNo: [input] PISO-CAN series board number (1~7)

Port: [input] CAN port number (1~2 or 1~4)

AllMACID: [output] All of the destination DeviceNet MAC IDs

DeviceCount: [output] The amount of the devices in the network

- **Return:**

“DNM_OPEN_ERROR”
“DNM_MASTER_STATE_ERROR”
“DNM_SENDMSG_ERROR”
“DNM_NOERROR”
(Please refer to Section 1.1 Error Code”).

1.3.35 DNM_GetOwnership

- **Description:**
This function is used to make the master port to get the ownership in DeviceNet network.
- **Syntax:**
DWORD DNM_GetOwnership(BYTE BoardNo, BYTE Port)
- **Parameter:**
BoardNo: [input] PISO-CAN series board number (1~7)
Port: [input] CAN port number (1~2 or 1~4)
- **Return:**
“DNM_OPEN_ERROR”
“DNM_MASTER_STATE_ERROR”
“DNM_GET_OWNERSHIP_ERROR”
“DNM_NOERROR”
(Please refer to "Section 1.1 Error Code").

1.3.36 DNM_CheckFaultNode

- **Description:**
This function is used to check any fault nodes in DeviceNet network.
- **Syntax:**
DWORD DNM_CheckFaultNode(BYTE BoardNo, BYTE Port)
- **Parameter:**
BoardNo: [input] PISO-CAN series board number (1~7)
Port: [input] CAN port number (1~2 or 1~4)
- **Return:**
“DNM_OPEN_ERROR”
“DNM_MASTER_STATE_ERROR”
“DNM_MASTER_NOT_GET_OWNERSHIP”
“DNM_SENDMSG_ERROR”
The amount of the fault node (0~63)

(Please refer to "Section 1.1 Error Code").

1.3.37 DNM_GetAllFaultNode

- **Description:**

This function is used to get the Serial No and the Vendor ID of all fault nodes in DeviceNet network.

- **Syntax:**

DWORD DNM_GetAllFaultNode(BYTE BoardNo, BYTE Port, WORD *VendorID, DWORD *SerialNo, BYTE *NodeCount)

- **Parameter:**

BoardNo: [input] PISO-CAN series board number (1~7)

Port: [input] CAN port number (1~2 or 1~4)

VendorID: [output] The VendorID of all fault nodes

SerialNo: [output] The SerialNo of all fault nodes

NodeCount: [output] The amount of all fault nodes

- **Return:**

"DNM_OPEN_ERROR"

"DNM_MASTER_STATE_ERROR"

"DNM_MASTER_NOT_GET_OWNERSHIP"

"DNM_NORESPONSE"

"DNM_SENDDMSG_ERROR"

"DNM_NOERROR"

(Please refer to "Section 1.1 Error Code").

1.3.38 DNM_ChangeFaultMACID

- **Description:**

The function is to change the MAC ID of the fault node in DeviceNet network if the slave device has the settable MAC ID.

- **Syntax:**

DWORD DNM_ChangeFaultMACID(BYTE BoardNo, BYTE Port, WORD VendorID, DWORD SerialNo, BYTE NewMacID)

- **Parameter:**

BoardNo: [input] PISO-CAN series board number (1~7)

Port: [input] CAN port number (1~2 or 1~4)

VendorID: [input] The VendorID of all fault nodes

SerialNo: [input] The SerialNo of all fault nodes

NewMACID: [input] The new MAC ID of the fault node

-
- **Return:**
"DNM_OPEN_ERROR"
"DNM_MASTER_STATE_ERROR"
"DNM_MASTER_NOT_GET_OWNERSHIP"
"DNM_SENDMSG_ERROR"
"DNM_NOERROR"
(Please refer to Section 1.1 Error Code").

1.3.39 DNM_GetDeviceStatus

- **Description:**
This function is used to check the status of the certain slave device.
- **Syntax:**
DWORD DNM_GetDeviceStatus(BYTE BoardNo,BYTE Port,BYTE DesMacID)
- **Parameter:**
BoardNo: [input] PISO-CAN series board number (1~7)
Port: [input] CAN port number (1~2 or 1~4)
DestMACID: [input] The destination DeviceNet MAC ID (0~63)
- **Return:**
"DNM_OPEN_ERROR"
"DNM_MACID_ERROR"
"DNM_MASTER_STATE_ERROR"
"DNM_DEVICE_NOT_IN_SCANLIST"
"DNM_EXPLICITMSG_NOT_CONFIG"
"DNM_POLL_NOT_CONFIG"
"DNM_BITSTROBE_NOT_CONFIG"
"DNM_COS_CYCLIC_NOT_CONFIG"
"DNM_DEVICE_ERROR"
"DNM_NOERROR"
(Please refer to "Section 1.1 Error Code").

1.3.40 DNM_SetPollFrequency

- **Description:**
This function is used to set the frequency of the Poll connection. The frequency is the refresh rate of Poll I/O signal. The frequency range is from 1 to 1000 Hz.
- **Syntax:**

DWORD DNM_SetPollFrequency(WORD Frequency)

- **Parameter:**
Frequency: [input] the Poll I/O refresh frequency (1~1000)
- **Return:**
The frequency you have set.

1.3.41 DNM_SetBitStrobeFrequency

- **Description:**
This function is used to set the frequency of the Bit-Strobe connection.
The frequency is the refresh rate of Bit-Strobe I/O signal. The frequency range is from 1 to 1000 Hz.
- **Syntax:**
DWORD DNM_SetBitStrobeFrequency(WORD Frequency)
- **Parameter:**
Frequency: [input] the Bit-Strobe I/O refresh frequency (1~1000)
- **Return:**
The frequency you have set.

2.PISO-CAN Series DeviceNet Library Demo for Linux

All of demo will not work normally if PCI linux driver would not be installed correctly. During the installation process of PCI linux driver, the install-scripts “ixpci.inst” will setup the correct kernel driver. After driver (version 0.7.6 or the later driver version) compiled and installation, the related demo programs, declaration header files for different development environments are presented as follows.

Table 2.1

Driver Name	Directory Path	File Name	Description
ixpci-0.7.6	examples/ pisocan200 or examples/ pisocan400	candnm_a	The demo are created for demonstrating how to use the CAN DeviceNet Master Library to apply the CAN DeviceNet communication protocol.

2.1 Demo code “candnm_a”

Using the CAN DeviceNet master library function to provide “Explicit Message”, “Poll”, “BitStrobe” and “COS/Cyclic CAN DeviceNet object connection. Before user referred to below steps for DeviceNet application, user should install the hardware (the connection of cable) and software (the linux driver of PISO-CAN series board) of DeviceNet master (PISO-CAN series) and slave device (for example the CAN-8224) well.

2.1.1 The DeviceNet Master Online

The section depicts the DeviceNet master online steps. Please refer to figure 2-1.

```

[root@localhost pisocan400]# ./candnm_a (1)Start of Application

/*****
/* Driver Version = 0.7.6
/* Device Net Library Version = 0.1.0 */
*****/

CAN Card Board Number(1~4) :1 (2)Input the Number of Board and Port
CAN Card Port Number(1~4) :3
0:125Kbps
1:250Kbps
2:500Kbps
CAN Baud(0~2) :0 (3)Input the Baud and MacID of CAN Master
CAN MacID(0~63) :10
CAN Card Online OK (4)DNM Online OK

```

Figure 2-1

2.1.2 The Explicit Message Application

The section depicts how to get the attribute (use demo item 'm' or 'n') value or set the attribute value (use demo item 'o') of DeviceNet slave devices via the Explicit connection. Please refer to figure 2-2 to get slave product name.

```

e
Please input slave node address(0~63):9 User could choice the item "e", "g"
Add Slave Device OK and "l" to configure and establish
g the connection of Explicit Message.
Please input slave node address(0~63):9
Configure Explicit Message OK
l
Please input slave node address(0~63):9
start Device OK

n
Please input slave node address(0~63):9 To choice item "n" and input slave
DNM Get Slave Product Name OK macid '9' to get slave product name.
Slave Product Name : I C P D A S - C A N - 8 x 2 4

```

Figure 2-2

2.1.3 Master Communicate With Slave Device

The demo “candnm_a” also provide function item to demonstrate how to communicate with slave device through the I/O Connection. The users should check the I/O connection mode that the slave device supports, then set the input and output data length. To use the function item “h”, “i”, “j” or “k” to finish the configuration. Then use function item “l” to start to communicate with slave device via the I/O connection. If the I/O connection is established, the user can read the data from the slave device. At the same time, the user can write the data to the slave device. For example user want to use “Poll” I/O connection to communicate with slave device CAN-8224, user could refer to figure 2-3, the figure depicts how to use “Poll” I/O to communicate with slave “CAN-8224” (DO module “i-8057” in slot 1 and DI module “i-8053” in slot2).

```
e
Please input slave node address(0~63):9 To add slave device
Add Slave Device OK

h
Please input slave node address(0~63):9 To configure Poll I/O
===== MapTable =====
  BufferID(DesMACID)   InstanceID-1   ConnectionID
0x9      0x0      0x44B
0x9      0x1      0x3C9
=====
Configure Poll Connection OK

l
Please input slave node address(0~63):9 To startup Poll I/O
Start Device OK

p
Please input slave node address(0~63):9 To send data to Slave
Please input Poll Data(hex):ff DO module "i-8057"
DNM Write Poll Output Data OK

q
Please input slave node address(0~63):9 To read data from Slave
DNM Read Poll Input Data OK DI module "i-8053"
Data[0] : 0xff Data[1] : 0x0
```

Figure 2-3