

Digital Low Pass Filter

The 8080 has three independent 2nd-order digital noise filters, LP0, LP1 & LP2, to remove noises as follows:

Channel	Low Pass Filter
A0	Low Pass Filter 0
B0	Low Pass Filter 0
A1	Low Pass Filter 1
B1	Low Pass Filter 1
A2	Low Pass Filter 2
B2	Low Pass Filter 2
A3	Low Pass Filter 2
B3	Low Pass Filter 2

The Low Pass Filter can be either disabled or programmable from 2 μ S to 65535 μ S.

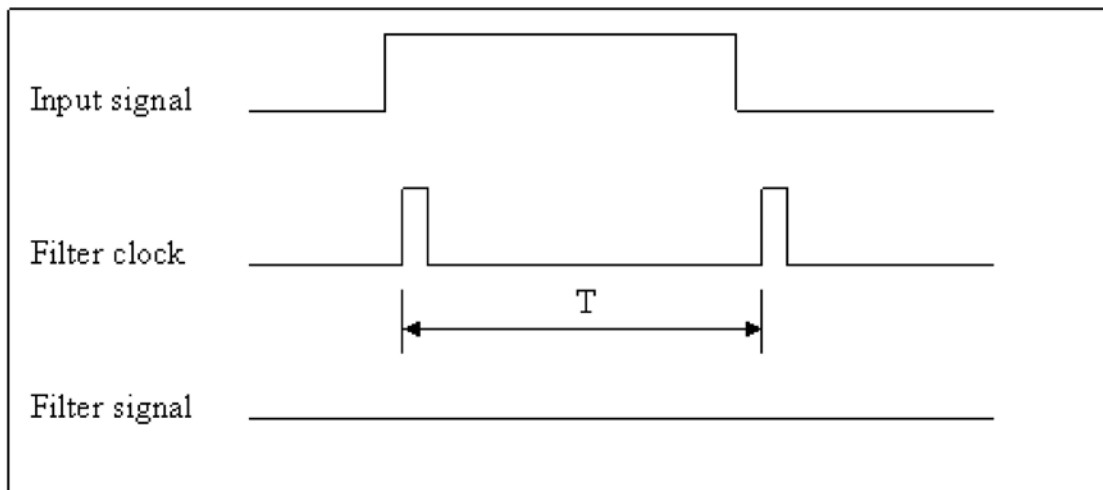
The Low Pass Filter will apply to all working modes, counter or frequency.

These 3 Low Pass Filters are disabled status in the default shipping. User defined program can be

used to issue a command to enable or disable the filters.

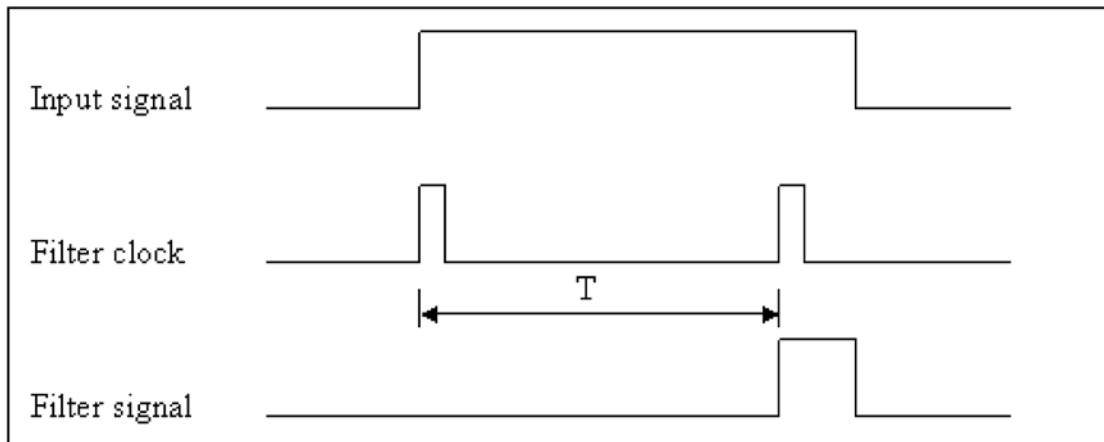
Assume that the filter clock of the Low Pass Filter is set to T, this clock is used to sample the input signal.

If one of the adjacent 2 samples is low, then the input signal will be removed as follows:



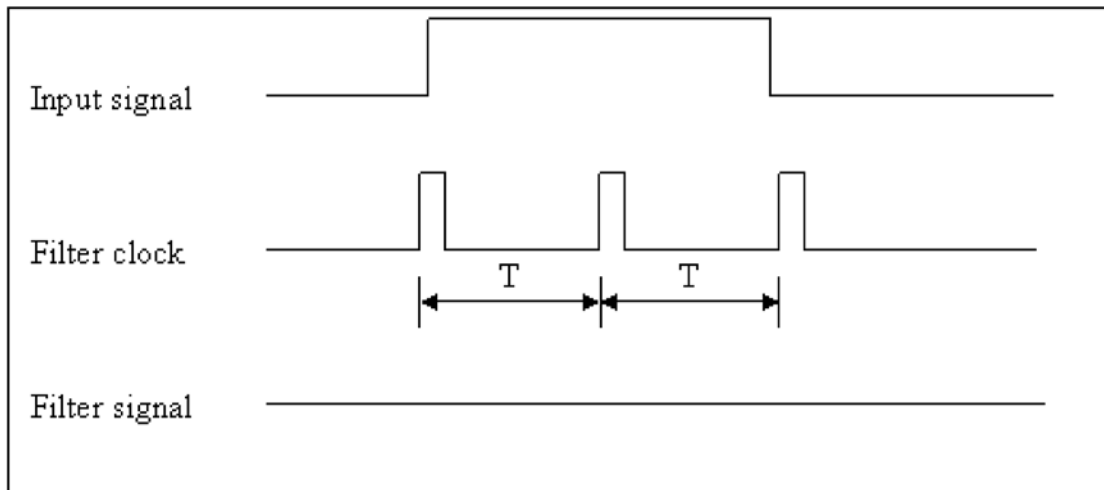
If the high width of the input signal is shorter than T, it will be filtered.

If the adjacent 2 samples are all HIGH, the input signal can pass as indicated below:



Note: the filter signal is shorter than the original input signal.

If the input signal is shorter than $2T$, it may be filtered in the following manner:



The relationship between the input signal and the filter signal is as follows:

if $(2T < \text{input signal})$, it will pass

if $(T \leq \text{input signal} \leq 2T)$, it may be filtered or passed

if $(\text{input signal} < T)$, it will be filtered

The software driver, 'i8080_SetLowPassUs (int Slot, int Channel, unsigned int Us)', provides an parameter, Us which can be used to set the Low Pass Filter as follows:

if $Us=1$ and $2T = 1\mu\text{S}$ then $T = 0.5\mu\text{S}$ and $\text{signal} \leq 0.5\mu\text{S}$ will be removed

if $Us=2$ and $2T = 2\mu\text{S}$ then $T = 1\mu\text{S}$ and $\text{signal} \leq 1\mu\text{S}$ will be removed

if $Us=N$, N from 1 to $0x7fff$ and $2T = N\mu\text{S}$ then $\text{signal} \leq (N/2)\mu\text{S}$ will be removed

The Low Pass Filter range can be configured from $1\mu\text{S}$ to $32767\mu\text{S}$. The high width of the signal $< (Us/2)$ will be removed.

For example, if you use a function generator as signal source, the 500Hz signal & 50/50 duty cycle will generate a 1000 μ S high & 1000 μ S low as follows:

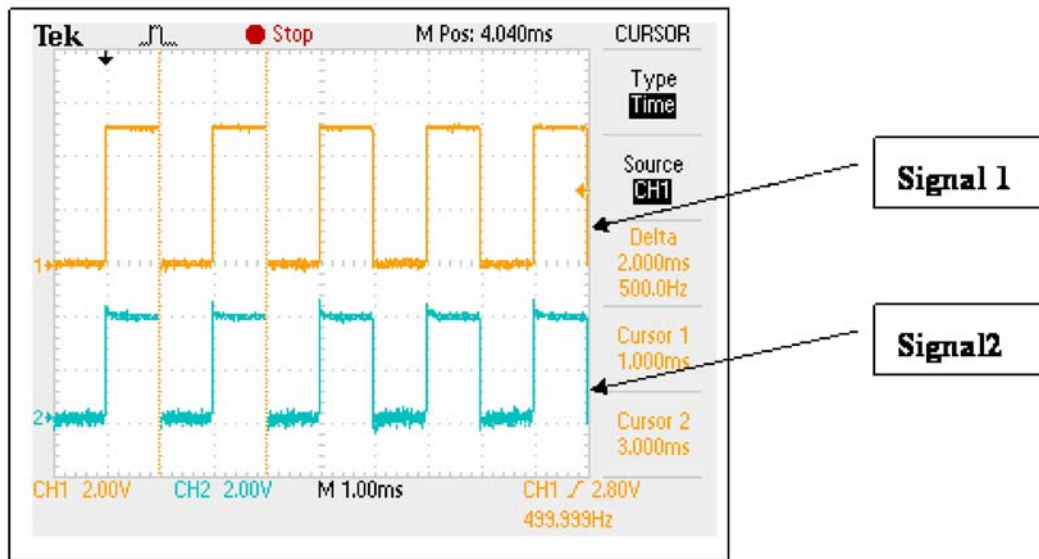


Figure 1 Input signal=500Hz & Low Pass Filter Disable

Signal 1 = input signal=500Hz, 50/50 duty cycle

Signal 2 = input signal after Xor and Low Pass Filter, now Xor=0 and Low Pass Filter is disable.

If the Low Pass Filter is disabled, signal 2 will be the same as signal 1 in the above diagram. If the Low Pass Filter is enabled, signal 2 will be shorter than signal 1 as shown below:

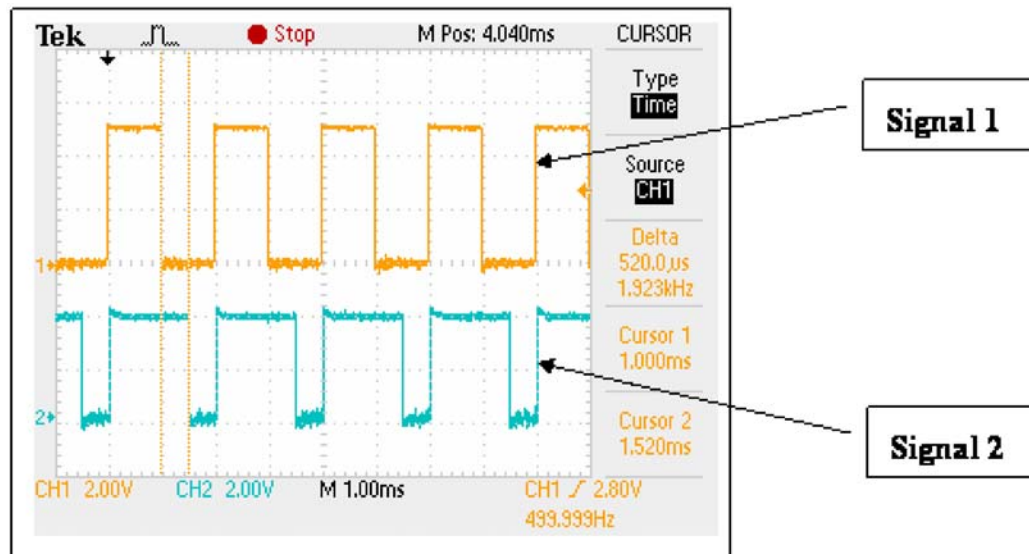


Figure 2 Input signal=500Hz & Low Pass Filter Enable=1 μ S

Signal 1 = input signal=500Hz, 50/50 duty cycle

Signal 2 = input signal after Xor and Low Pass Filter, now Xor=0 and the Low Pass Filter is

enabled.
Nearly all pulses are passed.

Now you can find that nearly all pulses are passed. If the input signal is increased to 600Hz, then some of the pulses are filtered as follows:

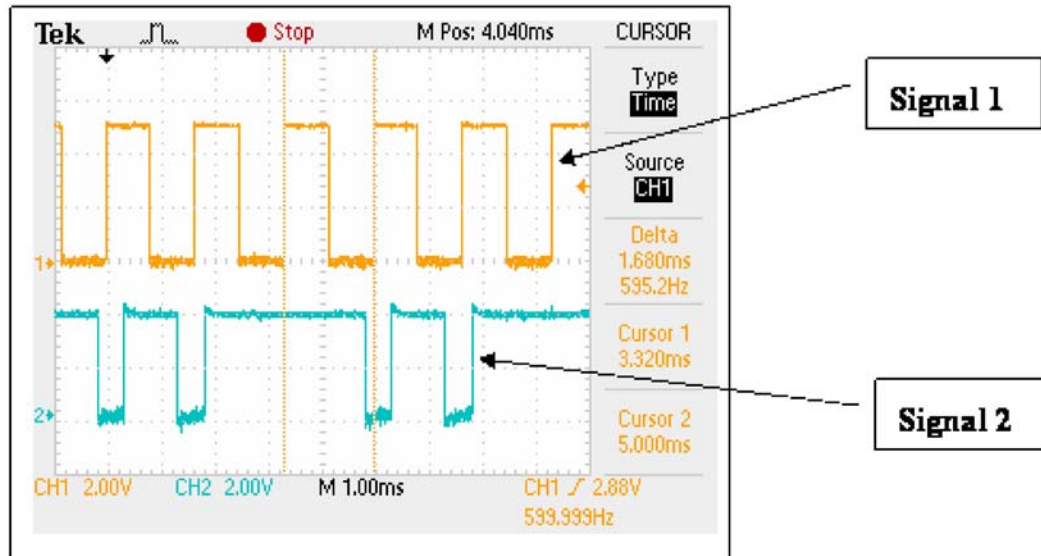


Figure 3 Input signal=600Hz & Low Pass Filter Enabled=1 μ S

Signal 1 = input signal=600Hz, 50/50 duty cycle.

Signal 2 = input signal after Xor and Low Pass Filter, now Xor =0 and Low Pass Filter is enabled.

Some pulses are filtered.

If the input signal is increased to 900Hz, then nearly all pulses are filtered as illustrated below:

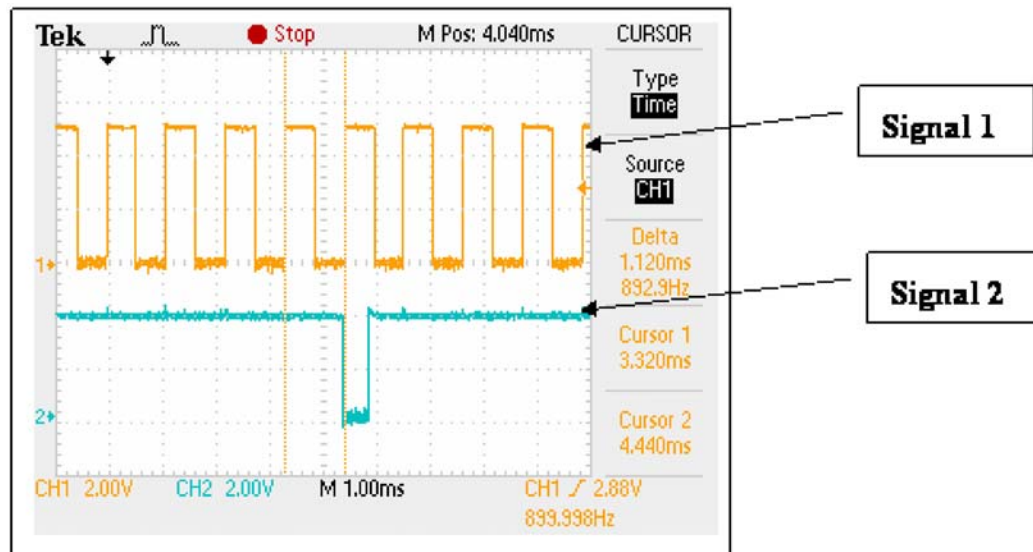


Figure 4 Input signal=900Hz & Low Pass Filter Enabled=1 μ S

Signal 1 = input signal=900Hz, 50/50 duty cycle

Signal 2 = input signal after Xor and Low Pass Filter, now Xor=0 and the Low Pass Filter is enabled.

Nearly all pulses are filtered.

Because there are some frequency offset errors in the internal crystal, there may be some noises when the input signal width = Low Pass Filter/2 as follows:

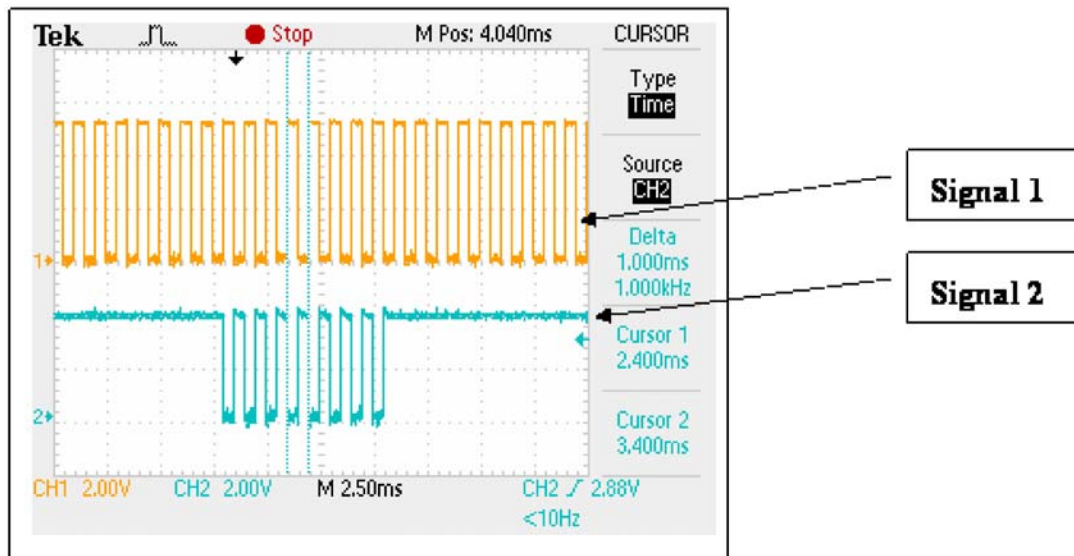


Figure 5 Input signal=1000Hz & Low Pass Filter Enabled=1 μ S

Signal 1 = input signal=1000Hz, 50/50 duty cycle à pulse width=500 μ S

Signal 2 = input signal after Xor and Low Pass Filter, now Xor=0 and the Low Pass Filter is enabled.

Signal Pulse=500 μ S=Low Pass Filter/2.

Nearly all pulses are filtered, but sometimes certain noises will not be filtered.

If the input signal is increased to 1100Hz, then all pulses will be filtered as shown in Figure 1-12:

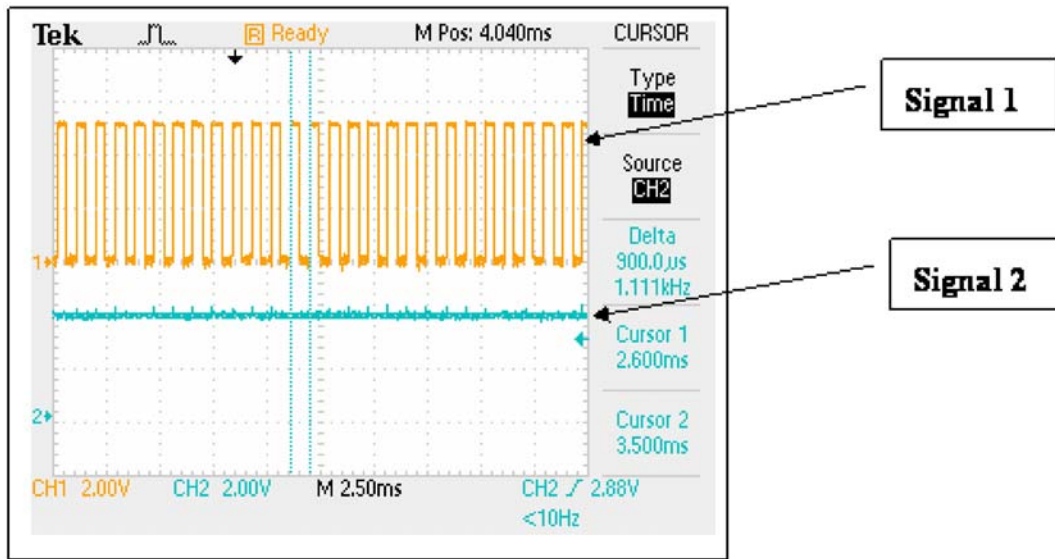


Figure 6 Input signal=1100Hz & Low Pass Filter Enabled=1µS

In summary, apply the minimum 1µS on Low Pass Filters.

The result of the signal being processed by the Low Pass Filter as follows:

Input signal frequency(Hz)	After Low Pass Filter processing	Reference
Input signal <500Hz (Low Pass Filter=1µS)	All signals will be passed	Figure 1
Input signal =500Hz (Low Pass Filter=1µS)	All signals should be passed	Figure 2
Input signal =600Hz (Low Pass Filter=1µS)	Some signals will be filtered and some will be passed	Figure 3
Input signal =900Hz (Low Pass Filter=1µS)	Many signals will be filtered and few will be passed	Figure 4
Input signal =1000Hz (Low Pass Filter=1µS)	Nearly all signals are filtered	Figure 5
Input signal =1100Hz (>1k Hz) (Low Pass Filter=1µS)	All signals will be filtered	Figure 6

For the same reason, if the signal pulse=Low Pass Filter, certain pulses may be filtered.

Therefore, it is recommended to set the cycle time of Low Pass Filter about 5% less than the cycle time of input signal pulse as shown below:

Input pulse =1 ms = 1000 µS à set Low Pass Filter <=950 µS

if Input pulse = 100 µS , set Low Pass Filter <= 95 µS

The minimum Low Pass Filter = 1 µS , input signal < 475K, 50/50 duty cycle

As a result, the maximum speed of the 8080 is recommended to 450K, 50/50 duty cycle